

Chih-Fan (Rich) Pai

Ph.D. Candidate, UC San Diego

Electrical and Computer Engineering

cfrpai@gmail.com +1 (858) 531-9377 <https://richpai.github.io>

Research Interests

Sequential decision-making under uncertainty, with emphasis on online control and prediction for dynamical systems, online learning and optimization, and reinforcement learning.

Education

University of California, San Diego

Sept. 2026 (Expected)

Ph.D., Electrical and Computer Engineering

J. Yang Scholarship

National Taiwan University

2020

M.S., Communication Engineering

Best Master's Thesis Award; Youth Thesis First Prize

National Yang Ming Chiao Tung University

2018

B.S., Electrical and Computer Engineering

Academic Excellence Award

Publications and Preprints

- **C.-F. Pai**, Y. Tang, and Y. Zheng. *Policy Optimization of Mixed $\mathcal{H}_2/\mathcal{H}_\infty$ Control: Benign Nonconvexity and Global Optimality*. Under review at *Automatica*.
- Y. Zheng, **C.-F. Pai**, and Y. Tang. *Benign Nonconvex Landscapes in Optimal and Robust Control, Parts I & II*. Under review at *IEEE Transactions on Automatic Control*.
- **C.-F. Pai**, X. Shang, J. Qian, and Y. Zheng. *Online Tracking with Predictions for Koopman-Linearizable Nonlinear Systems*. Learning for Dynamics and Control (L4DC), 2026.
- Y. Watanabe, **C.-F. Pai**, and Y. Zheng. *Semidefinite Programming Duality in Infinite-Horizon LQ Differential Games*. IEEE Conference on Decision and Control (CDC), 2025.
- Y. Zheng, **C.-F. Pai**, and Y. Tang. *Extended Convex Lifting for Policy Optimization of Optimal and Robust Control*. Learning for Dynamics and Control (L4DC), 2025.

Research Experience

University of California, San Diego

2023–Present

Research Assistant, Advisor: Professor Yang Zheng

- Developed online prediction algorithms for partially observed (marginally) stable linear dynamical systems under adversarial disturbances, achieving logarithmic regret with tailored predictive hints.
- Initiated a new research direction within the lab on adaptive regret minimization for online prediction and control under adversarial and/or nonstationary environments.
- Analyzed the dynamic regret of model predictive tracking algorithms for Koopman nonlinear systems.
- Established a new geometric and structural characterization of mixed $\mathcal{H}_2/\mathcal{H}_\infty$ control, proving benign nonconvexity and connecting policy optimization with classical Riccati theory and convex formulations.
- Developed Extended Convex Lifting, a unified framework revealing hidden convexity in nonconvex optimal and robust control, covering both state feedback static and output feedback dynamic policies.

National Taiwan University

2018–2020

Research Assistant, Advisor: Prof. See-May Phoong

- Conducted research in signal processing for communications, including time-varying channel estimation.

Selected Talks

• Decision-making in Uncertain Dynamic Environments

Invited seminar, CS Department, National Yang Ming Chiao Tung University, Dec. 2025.

• Online Non-stochastic Control: A Regret-Minimizing Approach

Invited presentation, DSC 291: Online Learning

Host: Professor Yoav Freund, UC San Diego, March 2025.

• Policy Optimization for Mixed Control: Benign Nonconvexity and Global Optimality

Southern California Control Workshop, University of Southern California, Nov. 2024.

Industry Experience

Qualcomm, Audio R&D Intern

Summer 2025

- Designed adaptive active noise cancellation algorithms under real-time hardware constraints.
- Balanced convergence, robustness, and stability using optimization and robust control theory.

Teaching Experience

Teaching Assistant, UC San Diego

ECE 285: Agentic AI and LLMs for Smart Grids

ECE 228: Machine Learning for Physical Applications

ECE 285: Semidefinite and Sum-of-Squares Optimization

ECE 171A: Linear Control System Theory

ECE 101: Linear Systems Fundamentals

- Led discussion sessions and developed instructional materials.

- Received consistently strong student evaluations.

Teaching Assistant, National Taiwan University

Linear Algebra (EE), Calculus (MATH), Digital and Multi-rate Signal Processing (CommE)

Programming and Computational Tools

Python, MATLAB, C/C++; PyTorch, TensorFlow; NumPy, Pandas, scikit-learn.